

# NAG Library Function Document

## nag\_real\_symm\_sparse\_eigensystem\_monit (f12fec)

**Note:** this function uses **optional parameters** to define choices in the problem specification. If you wish to use default settings for all of the optional parameters, then the option setting function `nag_real_symm_sparse_eigensystem_option` (f12fdc) need not be called. If, however, you wish to reset some or all of the settings please refer to Section 11 in `nag_real_symm_sparse_eigensystem_option` (f12fdc) for a detailed description of the specification of the optional parameters.

### 1 Purpose

`nag_real_symm_sparse_eigensystem_monit` (f12fec) can be used to return additional monitoring information during computation. It is in a suite of functions which includes `nag_real_symm_sparse_eigensystem_init` (f12fac), `nag_real_symm_sparse_eigensystem_iter` (f12fbc), `nag_real_symm_sparse_eigensystem_sol` (f12fcc) and `nag_real_symm_sparse_eigensystem_option` (f12fdc).

### 2 Specification

```
#include <nag.h>
#include <nagf12.h>

void nag_real_symm_sparse_eigensystem_monit (Integer *niter, Integer *nconv,
      double ritz[], double rzest[], const Integer icomm[],
      const double comm[])
```

### 3 Description

The suite of functions is designed to calculate some of the eigenvalues,  $\lambda$ , (and optionally the corresponding eigenvectors,  $x$ ) of a standard eigenvalue problem  $Ax = \lambda x$ , or of a generalized eigenvalue problem  $Ax = \lambda Bx$  of order  $n$ , where  $n$  is large and the coefficient matrices  $A$  and  $B$  are sparse, real and symmetric. The suite can also be used to find selected eigenvalues/eigenvectors of smaller scale dense, real and symmetric problems.

On an intermediate exit from `nag_real_symm_sparse_eigensystem_iter` (f12fbc) with **irevcm** = 4, `nag_real_symm_sparse_eigensystem_monit` (f12fec) may be called to return monitoring information on the progress of the Arnoldi iterative process. The information returned by `nag_real_symm_sparse_eigensystem_monit` (f12fec) is:

- the number of the current Arnoldi iteration;
- the number of converged eigenvalues at this point;
- the real and imaginary parts of the converged eigenvalues;
- the error bounds on the converged eigenvalues.

`nag_real_symm_sparse_eigensystem_monit` (f12fec) does not have an equivalent function from the ARPACK package which prints various levels of detail of monitoring information through an output channel controlled via an argument value (see Lehoucq *et al.* (1998) for details of ARPACK routines). `nag_real_symm_sparse_eigensystem_monit` (f12fec) should not be called at any time other than immediately following an **irevcm** = 4 return from `nag_real_symm_sparse_eigensystem_iter` (f12fbc).

### 4 References

Lehoucq R B (2001) Implicitly restarted Arnoldi methods and subspace iteration *SIAM Journal on Matrix Analysis and Applications* **23** 551–562

Lehoucq R B and Scott J A (1996) An evaluation of software for computing eigenvalues of sparse nonsymmetric matrices *Preprint MCS-P547-1195* Argonne National Laboratory

Lehoucq R B and Sorensen D C (1996) Deflation techniques for an implicitly restarted Arnoldi iteration *SIAM Journal on Matrix Analysis and Applications* **17** 789–821

Lehoucq R B, Sorensen D C and Yang C (1998) *ARPACK Users' Guide: Solution of Large-scale Eigenvalue Problems with Implicitly Restarted Arnoldi Methods* SIAM, Philadelphia

## 5 Arguments

- 1:    **niter** – Integer \* *Output*  
*On exit:* the number of the current Arnoldi iteration.
  
- 2:    **nconv** – Integer \* *Output*  
*On exit:* the number of converged eigenvalues so far.
  
- 3:    **ritz**[*dim*] – double *Output*  
**Note:** the dimension, *dim*, of the array **ritz** must be at least **ncv** (see nag\_real\_symm\_sparse\_eigensystem\_init (f12fac)).  
*On exit:* the first **nconv** locations of the array **ritz** contain the real converged approximate eigenvalues.
  
- 4:    **rzest**[*dim*] – double *Output*  
**Note:** the dimension, *dim*, of the array **rzest** must be at least **ncv** (see nag\_real\_symm\_sparse\_eigensystem\_init (f12fac)).  
*On exit:* the first **nconv** locations of the array **rzest** contain the Ritz estimates (error bounds) on the real **nconv** converged approximate eigenvalues.
  
- 5:    **icomm**[*dim*] – const Integer *Communication Array*  
**Note:** the dimension, *dim*, of the array **icomm** must be at least max(1, **lcomm**), where **lcomm** is passed to the setup function (see nag\_real\_symm\_sparse\_eigensystem\_init (f12fac)).  
*On entry:* the array **icomm** output by the preceding call to nag\_real\_symm\_sparse\_eigensystem\_iter (f12fbc).
  
- 6:    **comm**[*dim*] – const double *Communication Array*  
**Note:** the dimension, *dim*, of the array **comm** must be at least max(1, **lcomm**), where **lcomm** is passed to the setup function (see nag\_real\_symm\_sparse\_eigensystem\_init (f12fac)).  
*On entry:* the array **comm** output by the preceding call to nag\_real\_symm\_sparse\_eigensystem\_iter (f12fbc).

## 6 Error Indicators and Warnings

None.

## 7 Accuracy

A Ritz value,  $\lambda$ , is deemed to have converged if its Ritz estimate  $\leq \textbf{Tolerance} \times |\lambda|$ . The default **Tolerance** used is the *machine precision* given by nag\_machine\_precision (X02AJC).

## 8 Parallelism and Performance

nag\_real\_symm\_sparse\_eigensystem\_monit (f12fec) is not threaded in any implementation.

## 9 Further Comments

None.

## 10 Example

This example solves  $Kx = \lambda K_G x$  using the **Buckling** option (see nag\_real\_symm\_sparse\_eigensystem\_option (f12fdc), where  $K$  and  $K_G$  are obtained by the finite element method applied to the one-dimensional discrete Laplacian operator  $\frac{\partial^2 u}{\partial x^2}$  on  $[0, 1]$ , with zero Dirichlet boundary conditions using piecewise linear elements. The shift,  $\sigma$ , is a real number, and the operator used in the Buckling iterative process is  $OP = \text{inv}(K - \sigma K_G) \times K$  and  $B = K$ .

### 10.1 Program Text

```
/* nag_real_symm_sparse_eigensystem_monit (f12fec) Example Program.
*
* NAGPRODCODE Version.
*
* Copyright 2016 Numerical Algorithms Group.
*
* Mark 26, 2016.
*/

#include <math.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <stdio.h>
#include <nagf12.h>
#include <nagf16.h>

static void av(Integer, double *, double *);
static void my_dgtrf(Integer, double *, double *, double *,
                    double *, Integer *, Integer *);
static void my_dgttrs(Integer, double *, double *, double *,
                    double *, Integer *, double *, double *);

int main(void)
{
    /* Constants */
    Integer licomm = 140, imon = 1;

    /* Scalars */
    double estnrm, h, r1, r2, sigma;
    Integer exit_status, info, irevcm, j, lcomm, n, nconv, ncv;
    Integer nev, niter, nshift;
    /* Nag types */
    NagError fail;
    /* Arrays */
    double *dd = 0, *dl = 0, *du = 0, *du2 = 0, *comm = 0, *eigest = 0;
    double *eigv = 0, *resid = 0, *v = 0, *x2 = 0;
    Integer *icomm = 0, *ipiv = 0;
    /* Pointers */
    double *mx = 0, *x = 0, *y = 0;

    exit_status = 0;
    INIT_FAIL(fail);

    printf("nag_real_symm_sparse_eigensystem_monit (f12fec) Example "
           "Program Results\n");
    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%s[^\n] ");
#else
    scanf("%s[^\n] ");
#endif

    /* Read values for nx, nev and cnv from data file. */
}
```

```

#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%*[\n] ", &n, &nev, &ncv);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%*[\n] ", &n, &nev, &ncv);
#endif

/* Allocate memory */
lcomm = 3 * n + ncv * ncv + 8 * ncv + 60;
if (!(dd = NAG_ALLOC(n, double)) ||
    !(dl = NAG_ALLOC(n, double)) ||
    !(du = NAG_ALLOC(n, double)) ||
    !(du2 = NAG_ALLOC(n, double)) ||
    !(comm = NAG_ALLOC(lcomm, double)) ||
    !(eigv = NAG_ALLOC(ncv, double)) ||
    !(eigest = NAG_ALLOC(ncv, double)) ||
    !(resid = NAG_ALLOC(n, double)) ||
    !(v = NAG_ALLOC(n * ncv, double)) ||
    !(x2 = NAG_ALLOC(n, double)) ||
    !(icomm = NAG_ALLOC(lcomm, Integer)) ||
    !(ipiv = NAG_ALLOC(n, Integer)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Initialize communication arrays for problem using
   nag_real_symm_sparse_eigensystem_init (f12fac). */
nag_real_symm_sparse_eigensystem_init(n, nev, ncv, icomm, licomm, comm,
                                       lcomm, &fail);

if (fail.code != NE_NOERROR) {
    printf("Error from nag_real_symm_sparse_eigensystem_init "
          "(f12fac).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Select the problem type using
   nag_real_symm_sparse_eigensystem_option (f12fdc). */
nag_real_symm_sparse_eigensystem_option("generalized", icomm, comm, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_real_symm_sparse_eigensystem_option "
          "(f12fdc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Select the operating mode (Buckling) using
   nag_real_symm_sparse_eigensystem_option (f12fdc). */
nag_real_symm_sparse_eigensystem_option("buckling", icomm, comm, &fail);

/* Setup M and factorise */
h = 1.0 / (double) (n + 1);
r1 = 2.0 * h / 3.0;
r2 = h / 6.0;
sigma = 1.0;
for (j = 0; j <= n - 1; ++j) {
    dd[j] = 2.0 / h - sigma * r1;
    dl[j] = -1.0 / h - sigma * r2;
    du[j] = dl[j];
}
my_dgttrf(n, dl, dd, du, du2, ipiv, &info);

irevcm = 0;
REVCOMLOOP:
/* Repeated calls to reverse communication routine
   nag_real_symm_sparse_eigensystem_iter (f12fbc). */
nag_real_symm_sparse_eigensystem_iter(&irevcm, resid, v, &x, &y, &mx,
                                       &nshift, comm, icomm, &fail);

if (irevcm != 5) {
    if (irevcm == -1) {
        /* Perform  $y \leftarrow OP \cdot x = inv[K - SIGMA \cdot KG] \cdot K \cdot x$ . */

```

```

        av(n, x, x2);
        my_dgttrs(n, dl, dd, du, du2, ipiv, x2, y);
    }
    else if (irevcm == 1) {
        /* Perform y <-- OP*x = inv[K-sigma*KG]*K*x. */
        my_dgttrs(n, dl, dd, du, du2, ipiv, mx, y);
    }
    else if (irevcm == 2) {
        /* Perform y <--- K*x. */
        av(n, x, y);
    }
    else if (irevcm == 4 && imon == 1) {
        /* If imon=1, get monitoring information using
           nag_real_symm_sparse_eigensystem_monit (f12fec). */
        nag_real_symm_sparse_eigensystem_monit(&niter, &nconv, eigv, eigest,
                                                icomm, comm);

        /* Compute 2-norm of Ritz estimates using
           nag_dge_norm (f16rac). */
        nag_dge_norm(Nag_ColMajor, Nag_FrobeniusNorm, nev, 1, eigest, nev,
                     &estnrm, &fail);
        printf("Iteration %3" NAG_IFMT " ", niter);
        printf(" No. converged = %3" NAG_IFMT " ", nconv);
        printf(" norm of estimates = %17.8e\n", estnrm);
    }
    goto REVCOMLOOP;
}
if (fail.code == NE_NOERROR) {
    /* Post-Process using nag_real_symm_sparse_eigensystem_sol
       (f12fcc) to compute eigenvalues/vectors. */
    nag_real_symm_sparse_eigensystem_sol(&nconv, eigv, v, sigma, resid, v,
                                         comm, icomm, &fail);
    printf("\n The %4" NAG_IFMT " generalized Ritz values", nconv);
    printf(" closest to %8.4f are:\n\n", sigma);
    for (j = 0; j <= nconv - 1; ++j) {
        printf("%8" NAG_IFMT "%5s%12.4f\n", j + 1, "", eigv[j]);
    }
}
else {
    printf(" Error from nag_real_symm_sparse_eigensystem_iter "
           "(f12fbc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
    NAG_FREE(dd);
    NAG_FREE(dl);
    NAG_FREE(du);
    NAG_FREE(du2);
    NAG_FREE(comm);
    NAG_FREE(eigv);
    NAG_FREE(eigest);
    NAG_FREE(resid);
    NAG_FREE(v);
    NAG_FREE(x2);
    NAG_FREE(icomm);
    NAG_FREE(ipiv);

    return exit_status;
}

static void av(Integer n, double *v, double *y)
{
    /* Scalars */
    double h;
    Integer j;

    /* Function Body */
    h = (double) (n + 1);
    y[0] = h * (v[0] * 2.0 - v[1]);
    for (j = 1; j <= n - 2; ++j) {
        y[j] = h * (-v[j - 1] + v[j] * 2.0 - v[j + 1]);
    }
}

```

```

    }
    y[n - 1] = h * (-v[n - 2] + v[n - 1] * 2.0);
    return;
} /* av */

static void my_dgttrf(Integer n, double dl[], double d[],
                     double du[], double du2[], Integer ipiv[],
                     Integer *info)
{
    /* A simple C version of the Lapack routine dgttrf with argument
       checking removed */
    /* Scalars */
    double temp, fact;
    Integer i;
    /* Function Body */
    *info = 0;
    for (i = 0; i < n; ++i) {
        ipiv[i] = i;
    }
    for (i = 0; i < n - 2; ++i) {
        du2[i] = 0.0;
    }
    for (i = 0; i < n - 2; i++) {
        if (fabs(d[i]) >= fabs(dl[i])) {
            /* No row interchange required, eliminate dl[i]. */
            if (d[i] != 0.0) {
                fact = dl[i] / d[i];
                dl[i] = fact;
                d[i + 1] = d[i + 1] - fact * du[i];
            }
        }
        else {
            /* Interchange rows I and I+1, eliminate dl[I] */
            fact = d[i] / dl[i];
            d[i] = dl[i];
            dl[i] = fact;
            temp = du[i];
            du[i] = d[i + 1];
            d[i + 1] = temp - fact * d[i + 1];
            du2[i] = du[i + 1];
            du[i + 1] = -fact * du[i + 1];
            ipiv[i] = i + 1;
        }
    }
    if (n > 1) {
        i = n - 2;
        if (fabs(d[i]) >= fabs(dl[i])) {
            if (d[i] != 0.0) {
                fact = dl[i] / d[i];
                dl[i] = fact;
                d[i + 1] = d[i + 1] - fact * du[i];
            }
        }
        else {
            fact = d[i] / dl[i];
            d[i] = dl[i];
            dl[i] = fact;
            temp = du[i];
            du[i] = d[i + 1];
            d[i + 1] = temp - fact * d[i + 1];
            ipiv[i] = i + 1;
        }
    }
    /* Check for a zero on the diagonal of U. */
    for (i = 0; i < n; ++i) {
        if (d[i] == 0.0) {
            *info = i;
            goto END;
        }
    }
}
END:

```

```

    return;
}

static void my_dgttrs(Integer n, double dl[], double d[],
                     double du[], double du2[], Integer ipiv[],
                     double b[], double y[])
{
    /* A simple C version of the Lapack routine dgttrs with argument
       checking removed, the number of right-hand-sides=1, Trans='N' */
    /* Scalars */
    Integer i, ip;
    double temp;
    /* Solve L*x = b. */
    for (i = 0; i <= n - 1; ++i) {
        y[i] = b[i];
    }
    for (i = 0; i < n - 1; ++i) {
        ip = ipiv[i];
        temp = y[i + 1 - ip + i] - dl[i] * y[ip];
        y[i] = y[ip];
        y[i + 1] = temp;
    }
    /* Solve U*x = b. */
    y[n - 1] = y[n - 1] / d[n - 1];
    if (n > 1) {
        y[n - 2] = (y[n - 2] - du[n - 2] * y[n - 1]) / d[n - 2];
    }
    for (i = n - 3; i >= 0; --i) {
        y[i] = (y[i] - du[i] * y[i + 1] - du2[i] * y[i + 2]) / d[i];
    }
    return;
}

```

## 10.2 Program Data

nag\_real\_symm\_sparse\_eigensystem\_monit (f12fec) Example Program Data  
 100 4 10 : Values for n, nev and ncv

## 10.3 Program Results

nag\_real\_symm\_sparse\_eigensystem\_monit (f12fec) Example Program Results  
 Iteration 1, No. converged = 0, norm of estimates = 2.05343313e-06  
 Iteration 2, No. converged = 2, norm of estimates = 6.07599403e-11  
 Iteration 3, No. converged = 3, norm of estimates = 5.26525802e-15

The 4 generalized Ritz values closest to 1.0000 are:

1	9.8704
2	39.4912
3	88.8909
4	158.1175

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