

# NAG Library Function Document

## nag\_zggeev (f08wnc)

### 1 Purpose

nag\_zggeev (f08wnc) computes for a pair of  $n$  by  $n$  complex nonsymmetric matrices  $(A, B)$  the generalized eigenvalues and, optionally, the left and/or right generalized eigenvectors using the  $QZ$  algorithm. nag\_zggeev (f08wnc) is marked as *deprecated* by LAPACK; the replacement routine is nag\_zggeev3 (f08wqc) which makes better use of level 3 BLAS.

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_zggeev (Nag_OrderType order, Nag_LeftVecsType jobvl,
                 Nag_RightVecsType jobvr, Integer n, Complex a[], Integer pda,
                 Complex b[], Integer pdb, Complex alpha[], Complex beta[], Complex vl[],
                 Integer pdvl, Complex vr[], Integer pdvr, NagError *fail)
```

### 3 Description

A generalized eigenvalue for a pair of matrices  $(A, B)$  is a scalar  $\lambda$  or a ratio  $\alpha/\beta = \lambda$ , such that  $A - \lambda B$  is singular. It is usually represented as the pair  $(\alpha, \beta)$ , as there is a reasonable interpretation for  $\beta = 0$ , and even for both being zero.

The right generalized eigenvector  $v_j$  corresponding to the generalized eigenvalue  $\lambda_j$  of  $(A, B)$  satisfies

$$Av_j = \lambda_j Bv_j.$$

The left generalized eigenvector  $u_j$  corresponding to the generalized eigenvalue  $\lambda_j$  of  $(A, B)$  satisfies

$$u_j^H A = \lambda_j u_j^H B,$$

where  $u_j^H$  is the conjugate-transpose of  $u_j$ .

All the eigenvalues and, if required, all the eigenvectors of the complex generalized eigenproblem  $Ax = \lambda Bx$ , where  $A$  and  $B$  are complex, square matrices, are determined using the  $QZ$  algorithm. The complex  $QZ$  algorithm consists of three stages:

1.  $A$  is reduced to upper Hessenberg form (with real, non-negative subdiagonal elements) and at the same time  $B$  is reduced to upper triangular form.
2.  $A$  is further reduced to triangular form while the triangular form of  $B$  is maintained and the diagonal elements of  $B$  are made real and non-negative. This is the generalized Schur form of the pair  $(A, B)$ .

This function does not actually produce the eigenvalues  $\lambda_j$ , but instead returns  $\alpha_j$  and  $\beta_j$  such that

$$\lambda_j = \alpha_j / \beta_j, \quad j = 1, 2, \dots, n.$$

The division by  $\beta_j$  becomes your responsibility, since  $\beta_j$  may be zero, indicating an infinite eigenvalue.

3. If the eigenvectors are required they are obtained from the triangular matrices and then transformed back into the original coordinate system.

## 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (2012) *Matrix Computations* (4th Edition) Johns Hopkins University Press, Baltimore

Wilkinson J H (1979) Kronecker's canonical form and the *QZ* algorithm *Linear Algebra Appl.* **28** 285–303

## 5 Arguments

- 1: **order** – Nag\_OrderType *Input*  
*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.  
*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.
- 2: **jobvl** – Nag\_LeftVecsType *Input*  
*On entry:* if **jobvl** = Nag\_NotLeftVecs, do not compute the left generalized eigenvectors.  
If **jobvl** = Nag\_LeftVecs, compute the left generalized eigenvectors.  
*Constraint:* **jobvl** = Nag\_NotLeftVecs or Nag\_LeftVecs.
- 3: **jobvr** – Nag\_RightVecsType *Input*  
*On entry:* if **jobvr** = Nag\_NotRightVecs, do not compute the right generalized eigenvectors.  
If **jobvr** = Nag\_RightVecs, compute the right generalized eigenvectors.  
*Constraint:* **jobvr** = Nag\_NotRightVecs or Nag\_RightVecs.
- 4: **n** – Integer *Input*  
*On entry:* *n*, the order of the matrices *A* and *B*.  
*Constraint:* **n** ≥ 0.
- 5: **a**[*dim*] – Complex *Input/Output*  
**Note:** the dimension, *dim*, of the array **a** must be at least max(1, **pda** × **n**).  
The (*i*, *j*)th element of the matrix *A* is stored in  

$$\begin{aligned} &\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ &\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$
*On entry:* the matrix *A* in the pair (*A*, *B*).  
*On exit:* **a** has been overwritten.
- 6: **pda** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **a**.  
*Constraint:* **pda** ≥ max(1, **n**).
- 7: **b**[*dim*] – Complex *Input/Output*  
**Note:** the dimension, *dim*, of the array **b** must be at least max(1, **pdb** × **n**).

The  $(i, j)$ th element of the matrix  $B$  is stored in

$$\begin{aligned} &\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ &\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On entry:* the matrix  $B$  in the pair  $(A, B)$ .

*On exit:*  $\mathbf{b}$  has been overwritten.

- 8: **pdb** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array  $\mathbf{b}$ .

*Constraint:*  $\mathbf{pdb} \geq \max(1, \mathbf{n})$ .

- 9: **alpha[n]** – Complex *Output*

*On exit:* see the description of **beta**.

- 10: **beta[n]** – Complex *Output*

*On exit:*  $\mathbf{alpha}[j-1]/\mathbf{beta}[j-1]$ , for  $j = 1, 2, \dots, \mathbf{n}$ , will be the generalized eigenvalues.

**Note:** the quotients  $\mathbf{alpha}[j-1]/\mathbf{beta}[j-1]$  may easily overflow or underflow, and  $\mathbf{beta}[j-1]$  may even be zero. Thus, you should avoid naively computing the ratio  $\alpha_j/\beta_j$ . However,  $\max(|\alpha_j|)$  will always be less than and usually comparable with  $\|A\|_2$  in magnitude, and  $\max(|\beta_j|)$  will always be less than and usually comparable with  $\|B\|_2$ .

- 11: **vl[dim]** – Complex *Output*

**Note:** the dimension,  $\mathit{dim}$ , of the array  $\mathbf{vl}$  must be at least

$$\begin{aligned} &\max(1, \mathbf{pdvl} \times \mathbf{n}) \text{ when } \mathbf{jobvl} = \text{Nag\_LeftVecs}; \\ &1 \text{ otherwise.} \end{aligned}$$

The  $i$ th element of the  $j$ th vector is stored in

$$\begin{aligned} &\mathbf{vl}[(j-1) \times \mathbf{pdvl} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ &\mathbf{vl}[(i-1) \times \mathbf{pdvl} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On exit:* if  $\mathbf{jobvl} = \text{Nag\_LeftVecs}$ , the left generalized eigenvectors  $u_j$  are stored one after another in the columns of  $\mathbf{vl}$ , in the same order as the corresponding eigenvalues. Each eigenvector will be scaled so the largest component will have  $|\text{real part}| + |\text{imag. part}| = 1$ .

If  $\mathbf{jobvl} = \text{Nag\_NotLeftVecs}$ ,  $\mathbf{vl}$  is not referenced.

- 12: **pdvl** – Integer *Input*

*On entry:* the stride used in the array  $\mathbf{vl}$ .

*Constraints:*

$$\begin{aligned} &\text{if } \mathbf{jobvl} = \text{Nag\_LeftVecs}, \mathbf{pdvl} \geq \max(1, \mathbf{n}); \\ &\text{otherwise } \mathbf{pdvl} \geq 1. \end{aligned}$$

- 13: **vr[dim]** – Complex *Output*

**Note:** the dimension,  $\mathit{dim}$ , of the array  $\mathbf{vr}$  must be at least

$$\begin{aligned} &\max(1, \mathbf{pdvr} \times \mathbf{n}) \text{ when } \mathbf{jobvr} = \text{Nag\_RightVecs}; \\ &1 \text{ otherwise.} \end{aligned}$$

The  $i$ th element of the  $j$ th vector is stored in

$$\begin{aligned} &\mathbf{vr}[(j-1) \times \mathbf{pdvr} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ &\mathbf{vr}[(i-1) \times \mathbf{pdvr} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

On exit: if **jobvr** = Nag\_RightVecs, the right generalized eigenvectors  $v_j$  are stored one after another in the columns of **vr**, in the same order as the corresponding eigenvalues. Each eigenvector will be scaled so the largest component will have  $|\text{real part}| + |\text{imag. part}| = 1$ .

If **jobvr** = Nag\_NotRightVecs, **vr** is not referenced.

14: **pdvr** – Integer

*Input*

On entry: the stride used in the array **vr**.

Constraints:

if **jobvr** = Nag\_RightVecs, **pdvr**  $\geq \max(1, \mathbf{n})$ ;  
otherwise **pdvr**  $\geq 1$ .

15: **fail** – NagError \*

*Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle \text{value} \rangle$  had an illegal value.

### NE\_EIGENVECTORS

A failure occurred in nag\_ztgevc (f08yxc) while computing generalized eigenvectors.

### NE\_ENUM\_INT\_2

On entry, **jobvl** =  $\langle \text{value} \rangle$ , **pdvl** =  $\langle \text{value} \rangle$  and **n** =  $\langle \text{value} \rangle$ .

Constraint: if **jobvl** = Nag\_LeftVecs, **pdvl**  $\geq \max(1, \mathbf{n})$ ;  
otherwise **pdvl**  $\geq 1$ .

On entry, **jobvr** =  $\langle \text{value} \rangle$ , **pdvr** =  $\langle \text{value} \rangle$  and **n** =  $\langle \text{value} \rangle$ .

Constraint: if **jobvr** = Nag\_RightVecs, **pdvr**  $\geq \max(1, \mathbf{n})$ ;  
otherwise **pdvr**  $\geq 1$ .

### NE\_INT

On entry, **n** =  $\langle \text{value} \rangle$ .

Constraint: **n**  $\geq 0$ .

On entry, **pda** =  $\langle \text{value} \rangle$ .

Constraint: **pda**  $> 0$ .

On entry, **pdb** =  $\langle \text{value} \rangle$ .

Constraint: **pdb**  $> 0$ .

On entry, **pdvl** =  $\langle \text{value} \rangle$ .

Constraint: **pdvl**  $> 0$ .

On entry, **pdvr** =  $\langle \text{value} \rangle$ .

Constraint: **pdvr**  $> 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .

Constraint: **pdb**  $\geq \max(1, \mathbf{n})$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_ITERATION\_QZ**

The *QZ* iteration failed. No eigenvectors have been calculated but **alpha** and **beta** should be correct from element  $\langle value \rangle$ .

The *QZ* iteration failed with an unexpected error, please contact NAG.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

**7 Accuracy**

The computed eigenvalues and eigenvectors are exact for nearby matrices  $(A + E)$  and  $(B + F)$ , where

$$\|(E, F)\|_F = O(\epsilon)\|(A, B)\|_F,$$

and  $\epsilon$  is the *machine precision*. See Section 4.11 of Anderson *et al.* (1999) for further details.

**Note:** interpretation of results obtained with the *QZ* algorithm often requires a clear understanding of the effects of small changes in the original data. These effects are reviewed in Wilkinson (1979), in relation to the significance of small values of  $\alpha_j$  and  $\beta_j$ . It should be noted that if  $\alpha_j$  and  $\beta_j$  are **both** small for any  $j$ , it may be that no reliance can be placed on **any** of the computed eigenvalues  $\lambda_i = \alpha_i/\beta_i$ . You are recommended to study Wilkinson (1979) and, if in difficulty, to seek expert advice on determining the sensitivity of the eigenvalues to perturbations in the data.

**8 Parallelism and Performance**

nag\_zggeev (f08wnc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_zggeev (f08wnc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

**9 Further Comments**

The total number of floating-point operations is proportional to  $n^3$ .

The real analogue of this function is nag\_dggeev (f08wac).

## 10 Example

This example finds all the eigenvalues and right eigenvectors of the matrix pair  $(A, B)$ , where

$$A = \begin{pmatrix} -21.10 - 22.50i & 53.50 - 50.50i & -34.50 + 127.50i & 7.50 + 0.50i \\ -0.46 - 7.78i & -3.50 - 37.50i & -15.50 + 58.50i & -10.50 - 1.50i \\ 4.30 - 5.50i & 39.70 - 17.10i & -68.50 + 12.50i & -7.50 - 3.50i \\ 5.50 + 4.40i & 14.40 + 43.30i & -32.50 - 46.00i & -19.00 - 32.50i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1.00 - 5.00i & 1.60 + 1.20i & -3.00 + 0.00i & 0.00 - 1.00i \\ 0.80 - 0.60i & 3.00 - 5.00i & -4.00 + 3.00i & -2.40 - 3.20i \\ 1.00 + 0.00i & 2.40 + 1.80i & -4.00 - 5.00i & 0.00 - 3.00i \\ 0.00 + 1.00i & -1.80 + 2.40i & 0.00 - 4.00i & 4.00 - 5.00i \end{pmatrix}.$$

### 10.1 Program Text

```
/* nag_zggeev (f08wnc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <naga02.h>
#include <nagf08.h>
#include <nagm01.h>
#include <nagx02.h>
#include <nagx04.h>

#ifdef __cplusplus
extern "C"
{
#endif
    static Integer NAG_CALL compare(const Nag_Pointer a, const Nag_Pointer b);
    static Integer normalize_vectors(Integer n, Complex v[], Complex e[],
                                    size_t rank[], const char *title);
    static Integer sort_values (Integer n, Complex alpha[],
                               Complex beta[], Complex e[],
                               size_t rank[], double emod[]);
#ifdef __cplusplus
}
#endif

int main(void)
{
    /* Scalars */
    Integer i, j, n, ninf, pda, pdb, pdvl, pdvr;
    Integer exit_status = 0;

    /* Arrays */
    Complex *a = 0, *alpha = 0, *b = 0, *beta = 0, *vl = 0, *vr = 0;
    Complex *e = 0;
    double *emod = 0;
    size_t *rank = 0;
    char nag_enum_arg[40];

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;
    Nag_LeftVecsType jobvl;
    Nag_RightVecsType jobvr;
```

```

#ifdef NAG_COLUMN_MAJOR
#define A(I, J)  a[(J-1)*pda + I - 1]
#define B(I, J)  b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J)  a[(I-1)*pda + J - 1]
#define B(I, J)  b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_zggeev (f08wnc) Example Program Results\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%*[\n]", &n);
#else
    scanf("%" NAG_IFMT "%*[\n]", &n);
#endif
    if (n < 0) {
        printf("Invalid n\n");
        exit_status = 1;
        goto END;
    }

#ifdef _WIN32
    scanf_s(" %39s%*[\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf(" %39s%*[\n]", nag_enum_arg);
#endif
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    jobvl = (Nag_LeftVecsType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
    scanf_s(" %39s%*[\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf(" %39s%*[\n]", nag_enum_arg);
#endif
    jobvr = (Nag_RightVecsType) nag_enum_name_to_value(nag_enum_arg);

    pda = n;
    pdb = n;
    pdvl = (jobvl == Nag_LeftVecs ? n : 1);
    pdvr = (jobvr == Nag_RightVecs ? n : 1);

    /* Allocate memory */
    if (!(a = NAG_ALLOC(n * n, Complex)) ||
        !(alpha = NAG_ALLOC(n, Complex)) ||
        !(b = NAG_ALLOC(n * n, Complex)) ||
        !(beta = NAG_ALLOC(n, Complex)) ||
        !(vl = NAG_ALLOC(pdvl * pdvl, Complex)) ||
        !(e = NAG_ALLOC(n, Complex)) ||
        !(emod = NAG_ALLOC(n, double)) ||
        !(rank = NAG_ALLOC(n, size_t)) ||
        !(vr = NAG_ALLOC(pdvr * pdvr, Complex)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read in the matrices A and B */
    for (i = 1; i <= n; ++i)
        for (j = 1; j <= n; ++j)

```

```

#ifdef _WIN32
    scanf_s(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#else
    scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*[^\\n]");
#else
    scanf("%*[^\\n]");
#endif
    for (i = 1; i <= n; ++i)
        for (j = 1; j <= n; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
            scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*[^\\n]");
#else
    scanf("%*[^\\n]");
#endif

/* Solve the generalized eigenvalue problem using nag_zggeev (f08wnc). */
nag_zggeev(order, jobvl, jobvr, n, a, pda, b, pdb, alpha, beta, vl, pdvl, vr,
           pdvr, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zggeev (f08wnc).\\n%s\\n", fail.message);
    exit_status = 1;
    goto END;
}

printf("\\n      Eigenvalues\\n");
ninf = 0;
for (i = 0; i < n; ++i) {
    if (beta[i].re == 0.0) {
        ninf = ninf + 1;
        printf(" %4" NAG_IFMT "      Infinite eigenvalue\\n", i + 1);
    }
}
if (ninf==0) {
    /* Sort values by decreasing modulus and store in e[] */
    exit_status=sort_values (n, alpha, beta, e, rank, emod);
    for (i = 0; i < n; ++i) {
        printf(" %4" NAG_IFMT "      (%7.3f,%7.3f)\\n", i + 1, e[i].re, e[i].im);
    }
    if (jobvl == Nag_LeftVecs) {
        exit_status = normalize_vectors(n, vl, e, rank,
                                       "      Left eigenvectors (columns)");
    }
    if (jobvr == Nag_RightVecs && exit_status == 0) {
        exit_status = normalize_vectors(n, vr, e, rank,
                                       "      Right eigenvectors (columns)");
    }
}
}

END:
NAG_FREE(a);
NAG_FREE(alpha);
NAG_FREE(b);
NAG_FREE(beta);
NAG_FREE(vl);
NAG_FREE(vr);
NAG_FREE(e);
NAG_FREE(emod);
NAG_FREE(rank);

return exit_status;
}
static Integer normalize_vectors(Integer n, Complex v[], Complex e[],
                                size_t rank[], const char *title)

```

```

{
    Complex          scal;
    double           r, rr;
    Integer          errors = 0, i, j, k;
    Nag_OrderType    order;
    NagError         fail;

    INIT_FAIL(fail);

#ifdef NAG_COLUMN_MAJOR
#define V(I, J)  v[(J-1)*n + I - 1]
    order = Nag_ColMajor;
#else
#define V(I, J)  v[(I-1)*n + J - 1]
    order = Nag_RowMajor;
#endif
    /* Re-normalize the eigenvectors, largest absolute element real */
    for (i=1; i<=n; i++) {
        k = 0;
        r = -1.0;
        for (j=1; j<=n; j++) {
            rr = nag_complex_abs(V(j,i));
            if (rr>r) {
                r = rr;
                k = j;
            }
        }
        scal.re = V(k,i).re/(r*r);
        scal.im = -V(k,i).im/(r*r);
        for (j=1; j<=n; j++) {
            V(j,i) = nag_complex_multiply(V(j,i),scal);
        }
        V(k,i).re = 1.0;
        V(k,i).im = 0.0;
    }
    /* Sort eigenvectors according to rank */
    for (i=1; i<=n; i++) {
        for (j=1; j<=n; j++)
            e[j-1] = V(i,j);

        /* Sort eigenvector row i using nag_reorder_vector (m0lesc). */
        nag_reorder_vector((Pointer) e, (size_t) n, sizeof(Complex),
                           (ptrdiff_t) sizeof(Complex), rank, &fail);
        if (fail.code != NE_NOERROR) {
            printf("Error from nag_reorder_vector (m0lesc).\n%s\n", fail.message);
            errors = 5;
            goto END;
        }
        for (j=1; j<=n; j++)
            V(i,j) = e[j-1];
    }

    printf("\n");
    /* Print eigenvectors using nag_gen_complx_mat_print (x04dac). */
    fflush(stdout);
    nag_gen_complx_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                             n, v, n, title, 0, &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_gen_complx_mat_print (x04dac).\n%s\n",
              fail.message);
        errors = 6;
    }
}
#undef V
END:
    return errors;
}
static Integer sort_values (Integer n, Complex alpha[], Complex beta[],
                           Complex e[], size_t rank[], double emod[])
{
    Integer          i, exit_status = 0;

```

```

NagError      fail;

INIT_FAIL(fail);

for (i = 0; i < n; ++i) {
    /* nag_complex_divide (a02cdc): Quotient of two complex numbers;
    * nag_complex_abs (a02ddc): Moduli of complex number.
    */
    e[i] = nag_complex_divide(alpha[i], beta[i]);
    emod[i] = nag_complex_abs(e[i]);
}
/* Rank sort eigenvalues by absolute values using
* nag_rank_sort (m0ldsc).
*/
nag_rank_sort((Pointer) emod, (size_t) n, (ptrdiff_t) (sizeof(double)),
              compare, Nag_Descending, rank, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_rank_sort (m0ldsc).\n%s\n", fail.message);
    exit_status = 10;
    goto END;
}
/* Turn ranks into indices using nag_make_indices (m0lzac). */
nag_make_indices(rank, (size_t) n, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_make_indices (m0lzac).\n%s\n", fail.message);
    exit_status = 11;
    goto END;
}
/* Sort eigenvalues using nag_reorder_vector (m0lesc). */
nag_reorder_vector((Pointer) e, (size_t) n, sizeof(Complex),
                  (ptrdiff_t) sizeof(Complex), rank, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_reorder_vector (m0lesc).\n%s\n", fail.message);
    exit_status = 12;
    goto END;
}
END:
return exit_status;
}
static Integer NAG_CALL compare(const Nag_Pointer a, const Nag_Pointer b)
{
    double x = *((const double *) a) - *((const double *) b);
    return (x < 0.0 ? -1 : (x == 0.0 ? 0 : 1));
}

```

## 10.2 Program Data

nag\_zggeev (f08wnc) Example Program Data

```

4                                                    : n

Nag_NotLeftVecs                                     : jobvl
Nag_RightVecs                                       : jobvr

(-21.10,-22.50) ( 53.50,-50.50) (-34.50,127.50) ( 7.50, 0.50)
(-0.46, -7.78) (-3.50,-37.50) (-15.50, 58.50) (-10.50, -1.50)
( 4.30, -5.50) ( 39.70,-17.10) (-68.50, 12.50) (-7.50, -3.50)
( 5.50, 4.40) ( 14.40, 43.30) (-32.50,-46.00) (-19.00,-32.50) : A

( 1.00, -5.00) ( 1.60, 1.20) (-3.00, 0.00) ( 0.00, -1.00)
( 0.80, -0.60) ( 3.00, -5.00) (-4.00, 3.00) (-2.40, -3.20)
( 1.00, 0.00) ( 2.40, 1.80) (-4.00, -5.00) ( 0.00, -3.00)
( 0.00, 1.00) (-1.80, 2.40) ( 0.00, -4.00) ( 4.00, -5.00) : B

```

### 10.3 Program Results

nag\_zggeev (f08wnc) Example Program Results

```

Eigenvalues
1      (  3.000, -9.000)
2      (  4.000, -5.000)
3      (  2.000, -5.000)
4      (  3.000, -1.000)

Right eigenvectors (columns)
      1      2      3      4
1  1.0000  1.0000  1.0000  1.0000
   0.0000  0.0000  0.0000  0.0000

2  0.1600  0.0089  0.0046  0.1600
   -0.1200 -0.0067 -0.0034 -0.1200

3  0.1200 -0.0333  0.0629  0.1200
   0.1600 -0.0000  0.0000 -0.1600

4 -0.1600 -0.0000 -0.0000  0.1600
   0.1200  0.1556  0.0629  0.1200

```

---