

# NAG Library Function Document

## nag\_dsbtrd (f08hec)

### 1 Purpose

nag\_dsbtrd (f08hec) reduces a real symmetric band matrix to tridiagonal form.

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_dsbtrd (Nag_OrderType order, Nag_VectType vect, Nag_UploType uplo,
                 Integer n, Integer kd, double ab[], Integer pdab, double d[],
                 double e[], double q[], Integer pdq, NagError *fail)
```

### 3 Description

nag\_dsbtrd (f08hec) reduces a symmetric band matrix  $A$  to symmetric tridiagonal form  $T$  by an orthogonal similarity transformation:

$$T = Q^T A Q.$$

The orthogonal matrix  $Q$  is determined as a product of Givens rotation matrices, and may be formed explicitly by the function if required.

The function uses a vectorizable form of the reduction, due to Kaufman (1984).

### 4 References

Kaufman L (1984) Banded eigenvalue solvers on vector machines *ACM Trans. Math. Software* **10** 73–86

Parlett B N (1998) *The Symmetric Eigenvalue Problem* SIAM, Philadelphia

### 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **vect** – Nag\_VectType *Input*

*On entry:* indicates whether  $Q$  is to be returned.

**vect** = Nag\_FormQ  
 $Q$  is returned.

**vect** = Nag\_UpdateQ  
 $Q$  is updated (and the array **q** must contain a matrix on entry).

**vect** = Nag\_DoNotForm  
 $Q$  is not required.

*Constraint:* **vect** = Nag\_FormQ, Nag\_UpdateQ or Nag\_DoNotForm.

- 3: **uplo** – Nag\_UploType *Input*  
*On entry:* indicates whether the upper or lower triangular part of  $A$  is stored.  
**uplo** = Nag\_Upper  
The upper triangular part of  $A$  is stored.  
**uplo** = Nag\_Lower  
The lower triangular part of  $A$  is stored.  
*Constraint:* **uplo** = Nag\_Upper or Nag\_Lower.
- 4: **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrix  $A$ .  
*Constraint:* **n**  $\geq 0$ .
- 5: **kd** – Integer *Input*  
*On entry:* if **uplo** = Nag\_Upper, the number of superdiagonals,  $k_d$ , of the matrix  $A$ .  
If **uplo** = Nag\_Lower, the number of subdiagonals,  $k_d$ , of the matrix  $A$ .  
*Constraint:* **kd**  $\geq 0$ .
- 6: **ab**[*dim*] – double *Input/Output*  
**Note:** the dimension, *dim*, of the array **ab** must be at least  $\max(1, \mathbf{pdab} \times \mathbf{n})$ .  
*On entry:* the upper or lower triangle of the  $n$  by  $n$  symmetric band matrix  $A$ .  
This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements of  $A_{ij}$ , depends on the **order** and **uplo** arguments as follows:  
if **order** = Nag\_ColMajor and **uplo** = Nag\_Upper,  
 $A_{ij}$  is stored in **ab**[ $k_d + i - j + (j - 1) \times \mathbf{pdab}$ ], for  $j = 1, \dots, n$  and  $i = \max(1, j - k_d), \dots, j$ ;  
if **order** = Nag\_ColMajor and **uplo** = Nag\_Lower,  
 $A_{ij}$  is stored in **ab**[ $i - j + (j - 1) \times \mathbf{pdab}$ ], for  $j = 1, \dots, n$  and  $i = j, \dots, \min(n, j + k_d)$ ;  
if **order** = Nag\_RowMajor and **uplo** = Nag\_Upper,  
 $A_{ij}$  is stored in **ab**[ $j - i + (i - 1) \times \mathbf{pdab}$ ], for  $i = 1, \dots, n$  and  $j = i, \dots, \min(n, i + k_d)$ ;  
if **order** = Nag\_RowMajor and **uplo** = Nag\_Lower,  
 $A_{ij}$  is stored in **ab**[ $k_d + j - i + (i - 1) \times \mathbf{pdab}$ ], for  $i = 1, \dots, n$  and  $j = \max(1, i - k_d), \dots, i$ .  
*On exit:* **ab** is overwritten by values generated during the reduction to tridiagonal form.  
The first superdiagonal or subdiagonal and the diagonal of the tridiagonal matrix  $T$  are returned in **ab** using the same storage format as described above.
- 7: **pdab** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) of the matrix  $A$  in the array **ab**.  
*Constraint:* **pdab**  $\geq \max(1, \mathbf{kd} + 1)$ .
- 8: **d**[**n**] – double *Output*  
*On exit:* the diagonal elements of the tridiagonal matrix  $T$ .

9: **e[n – 1]** – double *Output*

*On exit:* the off-diagonal elements of the tridiagonal matrix  $T$ .

10: **q[dim]** – double *Input/Output*

**Note:** the dimension,  $dim$ , of the array **q** must be at least

$\max(1, \mathbf{pdq} \times \mathbf{n})$  when **vect** = Nag\_FormQ or Nag\_UpdateQ;  
1 when **vect** = Nag\_DoNotForm.

The  $(i, j)$ th element of the matrix  $Q$  is stored in

**q**[( $j - 1$ )  $\times$  **pdq** +  $i - 1$ ] when **order** = Nag\_ColMajor;  
**q**[( $i - 1$ )  $\times$  **pdq** +  $j - 1$ ] when **order** = Nag\_RowMajor.

*On entry:* if **vect** = Nag\_UpdateQ, **q** must contain the matrix formed in a previous stage of the reduction (for example, the reduction of a banded symmetric-definite generalized eigenproblem); otherwise **q** need not be set.

*On exit:* if **vect** = Nag\_FormQ or Nag\_UpdateQ, the  $n$  by  $n$  matrix  $Q$ .

If **vect** = Nag\_DoNotForm, **q** is not referenced.

11: **pdq** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **q**.

*Constraints:*

if **vect** = Nag\_FormQ or Nag\_UpdateQ, **pdq**  $\geq \max(1, \mathbf{n})$ ;  
if **vect** = Nag\_DoNotForm, **pdq**  $\geq 1$ .

12: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_ENUM\_INT\_2

On entry, **vect** =  $\langle value \rangle$ , **pdq** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .

Constraint: if **vect** = Nag\_FormQ or Nag\_UpdateQ, **pdq**  $\geq \max(1, \mathbf{n})$ ;  
if **vect** = Nag\_DoNotForm, **pdq**  $\geq 1$ .

### NE\_INT

On entry, **kd** =  $\langle value \rangle$ .

Constraint: **kd**  $\geq 0$ .

On entry, **n** =  $\langle value \rangle$ .

Constraint: **n**  $\geq 0$ .

On entry, **pdab** =  $\langle value \rangle$ .

Constraint: **pdab**  $> 0$ .

On entry, **pdq** =  $\langle value \rangle$ .  
 Constraint: **pdq** > 0.

## NE\_INT\_2

On entry, **pdab** =  $\langle value \rangle$  and **kd** =  $\langle value \rangle$ .  
 Constraint: **pdab**  $\geq \max(1, \mathbf{kd} + 1)$ .

## NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.  
 See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

## NE\_NO\_LICENCE

Your licence key may have expired or may not have been installed correctly.  
 See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

## 7 Accuracy

The computed tridiagonal matrix  $T$  is exactly similar to a nearby matrix  $(A + E)$ , where

$$\|E\|_2 \leq c(n)\epsilon\|A\|_2,$$

$c(n)$  is a modestly increasing function of  $n$ , and  $\epsilon$  is the *machine precision*.

The elements of  $T$  themselves may be sensitive to small perturbations in  $A$  or to rounding errors in the computation, but this does not affect the stability of the eigenvalues and eigenvectors.

The computed matrix  $Q$  differs from an exactly orthogonal matrix by a matrix  $E$  such that

$$\|E\|_2 = O(\epsilon),$$

where  $\epsilon$  is the *machine precision*.

## 8 Parallelism and Performance

nag\_dsbtrd (f08hec) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_dsbtrd (f08hec) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The total number of floating-point operations is approximately  $6n^2k$  if **vect** = Nag\_DoNotForm with  $3n^3(k-1)/k$  additional operations if **vect** = Nag\_FormQ.

The complex analogue of this function is nag\_zhbtrd (f08hsc).

## 10 Example

This example computes all the eigenvalues and eigenvectors of the matrix  $A$ , where

$$A = \begin{pmatrix} 4.99 & 0.04 & 0.22 & 0.00 \\ 0.04 & 1.05 & -0.79 & 1.04 \\ 0.22 & -0.79 & -2.31 & -1.30 \\ 0.00 & 1.04 & -1.30 & -0.43 \end{pmatrix}.$$

Here  $A$  is symmetric and is treated as a band matrix. The program first calls `nag_dsbtrd` (f08hec) to reduce  $A$  to tridiagonal form  $T$ , and to form the orthogonal matrix  $Q$ ; the results are then passed to `nag_dsteqr` (f08jec) which computes the eigenvalues and eigenvectors of  $A$ .

### 10.1 Program Text

```
/* nag_dsbtrd (f08hec) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, j, k, kd, n, pdab, pdz, d_len, e_len;
    Integer exit_status = 0;
    NagError fail;
    Nag_UploType uplo;
    Nag_OrderType order;
    /* Arrays */
    char nag_enum_arg[40];
    double *ab = 0, *d = 0, *e = 0, *z = 0;

#ifdef NAG_COLUMN_MAJOR
#define AB_UPPER(I, J) ab[(J - 1) * pdab + k + I - J - 1]
#define AB_LOWER(I, J) ab[(J - 1) * pdab + I - J]
#define Z(I, J) z[(J - 1) * pdz + I - 1]
    order = Nag_ColMajor;
#else
#define AB_UPPER(I, J) ab[(I - 1) * pdab + J - I]
#define AB_LOWER(I, J) ab[(I - 1) * pdab + k + J - I - 1]
#define Z(I, J) z[(I - 1) * pdz + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_dsbtrd (f08hec) Example Program Results\n\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n] ");
#else
    scanf("%*[\n] ");
#endif
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%*[\n] ", &n, &kd);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%*[\n] ", &n, &kd);
#endif
}
```

```

pdab = kd + 1;
pdz = n;
d_len = n;
e_len = n - 1;

/* Allocate memory */
if (!(ab = NAG_ALLOC(pdab * n, double)) ||
    !(d = NAG_ALLOC(d_len, double)) ||
    !(e = NAG_ALLOC(e_len, double)) || !(z = NAG_ALLOC(pdz * n, double)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Read A from data file */
#ifdef _WIN32
    scanf_s("%39s%[\n] ", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf("%39s%[\n] ", nag_enum_arg);
#endif
/* nag_enum_name_to_value (x04nac).
 * Converts NAG enum member name to value
 */
uplo = (Nag_UploType) nag_enum_name_to_value(nag_enum_arg);
k = kd + 1;
if (uplo == Nag_Upper) {
    for (i = 1; i <= n; ++i) {
        for (j = i; j <= MIN(i + kd, n); ++j)
#ifdef _WIN32
            scanf_s("%lf", &AB_UPPER(i, j));
#else
            scanf("%lf", &AB_UPPER(i, j));
#endif
    }
#ifdef _WIN32
    scanf_s("%*[\n] ");
#else
    scanf("%*[\n] ");
#endif
}
else {
    for (i = 1; i <= n; ++i) {
        for (j = MAX(1, i - kd); j <= i; ++j)
#ifdef _WIN32
            scanf_s("%lf", &AB_LOWER(i, j));
#else
            scanf("%lf", &AB_LOWER(i, j));
#endif
    }
#ifdef _WIN32
    scanf_s("%*[\n] ");
#else
    scanf("%*[\n] ");
#endif
}

/* Reduce A to tridiagonal form */
/* nag_dsbtrd (f08hec).
 * Orthogonal reduction of real symmetric band matrix to
 * symmetric tridiagonal form
 */
nag_dsbtrd(order, Nag_FormQ, uplo, n, kd, ab, pdab, d, e, z, pdz, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_dsbtrd (f08hec).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Calculate all the eigenvalues and eigenvectors of A */
/* nag_dsteqr (f08jec).
 * All eigenvalues and eigenvectors of real symmetric

```

```

    * tridiagonal matrix, reduced from real symmetric matrix
    * using implicit QL or QR
    */
nag_dsteqr(order, Nag_UpdateZ, n, d, e, z, pdz, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_dsteqr (f08jec).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Normalize the eigenvectors */
for (j = 1; j <= n; j++) {
    for (i = n; i >= 1; i--) {
        z(i, j) = z(i, j) / z(1, j);
    }
}
/* Print eigenvalues and eigenvectors */
printf("Eigenvalues\n");
for (i = 1; i <= n; ++i)
    printf("%8.4f%s", d[i - 1], i % 8 == 0 ? "\n" : " ");
printf("\n\n");
/* nag_gen_real_mat_print (x04cac).
 * Print real general matrix (easy-to-use)
 */
fflush(stdout);
nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, n,
                        z, pdz, "Eigenvectors", 0, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_gen_real_mat_print (x04cac).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
NAG_FREE(ab);
NAG_FREE(d);
NAG_FREE(e);
NAG_FREE(z);

return exit_status;
}

```

## 10.2 Program Data

```

nag_dsbtrd (f08hec) Example Program Data
  4  2          :Values of n and kd
  Nag_Lower      :Value of uplo
  4.99
  0.04  1.05
  0.22 -0.79 -2.31
      1.04 -1.30 -0.43 :End of matrix A

```

## 10.3 Program Results

nag\_dsbtrd (f08hec) Example Program Results

```

Eigenvalues
-2.9943 -0.7000  1.9974  4.9969

Eigenvectors
      1      2      3      4
1      1.0000  1.0000  1.0000  1.0000
2     -2.6092 -36.0739  71.4695  0.0020
3    -35.8180 -19.3048 -26.5971  0.0311
4    -17.1000  45.9991  44.8645 -0.0071

```

---