

# NAG Library Function Document

## nag\_zpttrs (f07jsc)

### 1 Purpose

nag\_zpttrs (f07jsc) computes the solution to a complex system of linear equations  $AX = B$ , where  $A$  is an  $n$  by  $n$  Hermitian positive definite tridiagonal matrix and  $X$  and  $B$  are  $n$  by  $r$  matrices, using the  $LDL^H$  factorization returned by nag\_zpttrf (f07jrc).

### 2 Specification

```
#include <nag.h>
#include <nagf07.h>

void nag_zpttrs (Nag_OrderType order, Nag_UploType uplo, Integer n,
                 Integer nrhs, const double d[], const Complex e[], Complex b[],
                 Integer pdb, NagError *fail)
```

### 3 Description

nag\_zpttrs (f07jsc) should be preceded by a call to nag\_zpttrf (f07jrc), which computes a modified Cholesky factorization of the matrix  $A$  as

$$A = LDL^H,$$

where  $L$  is a unit lower bidiagonal matrix and  $D$  is a diagonal matrix, with positive diagonal elements. nag\_zpttrs (f07jsc) then utilizes the factorization to solve the required equations. Note that the factorization may also be regarded as having the form  $U^H DU$ , where  $U$  is a unit upper bidiagonal matrix.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

### 5 Arguments

- 1: **order** – Nag\_OrderType *Input*  
*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.  
*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.
- 2: **uplo** – Nag\_UploType *Input*  
*On entry:* specifies the form of the factorization as follows:  
**uplo** = Nag\_Upper  
 $A = U^H DU$ .  
**uplo** = Nag\_Lower  
 $A = LDL^H$ .  
*Constraint:* **uplo** = Nag\_Upper or Nag\_Lower.

- 3:    **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrix  $A$ .  
*Constraint:*  $n \geq 0$ .
- 4:    **nrhs** – Integer *Input*  
*On entry:*  $r$ , the number of right-hand sides, i.e., the number of columns of the matrix  $B$ .  
*Constraint:*  $\mathbf{nrhs} \geq 0$ .
- 5:    **d**[ $dim$ ] – const double *Input*  
**Note:** the dimension,  $dim$ , of the array **d** must be at least  $\max(1, \mathbf{n})$ .  
*On entry:* must contain the  $n$  diagonal elements of the diagonal matrix  $D$  from the  $LDL^H$  or  $U^H DU$  factorization of  $A$ .
- 6:    **e**[ $dim$ ] – const Complex *Input*  
**Note:** the dimension,  $dim$ , of the array **e** must be at least  $\max(1, \mathbf{n} - 1)$ .  
*On entry:* if **uplo** = Nag\_Upper, **e** must contain the  $(n - 1)$  superdiagonal elements of the unit upper bidiagonal matrix  $U$  from the  $U^H DU$  factorization of  $A$ .  
If **uplo** = Nag\_Lower, **e** must contain the  $(n - 1)$  subdiagonal elements of the unit lower bidiagonal matrix  $L$  from the  $LDL^H$  factorization of  $A$ .
- 7:    **b**[ $dim$ ] – Complex *Input/Output*  
**Note:** the dimension,  $dim$ , of the array **b** must be at least  
 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$  when **order** = Nag\_ColMajor;  
 $\max(1, \mathbf{n} \times \mathbf{pdb})$  when **order** = Nag\_RowMajor.  
The  $(i, j)$ th element of the matrix  $B$  is stored in  
 $\mathbf{b}[(j - 1) \times \mathbf{pdb} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{b}[(i - 1) \times \mathbf{pdb} + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* the  $n$  by  $r$  matrix of right-hand sides  $B$ .  
*On exit:* the  $n$  by  $r$  solution matrix  $X$ .
- 8:    **pdb** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.  
*Constraints:*  
if **order** = Nag\_ColMajor,  $\mathbf{pdb} \geq \max(1, \mathbf{n})$ ;  
if **order** = Nag\_RowMajor,  $\mathbf{pdb} \geq \max(1, \mathbf{nrhs})$ .
- 9:    **fail** – NagError \* *Input/Output*  
The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

**NE\_BAD\_PARAM**

On entry, argument  $\langle value \rangle$  had an illegal value.

**NE\_INT**

On entry,  $\mathbf{n} = \langle value \rangle$ .

Constraint:  $\mathbf{n} \geq 0$ .

On entry,  $\mathbf{nrhs} = \langle value \rangle$ .

Constraint:  $\mathbf{nrhs} \geq 0$ .

On entry,  $\mathbf{pdb} = \langle value \rangle$ .

Constraint:  $\mathbf{pdb} > 0$ .

**NE\_INT\_2**

On entry,  $\mathbf{pdb} = \langle value \rangle$  and  $\mathbf{n} = \langle value \rangle$ .

Constraint:  $\mathbf{pdb} \geq \max(1, \mathbf{n})$ .

On entry,  $\mathbf{pdb} = \langle value \rangle$  and  $\mathbf{nrhs} = \langle value \rangle$ .

Constraint:  $\mathbf{pdb} \geq \max(1, \mathbf{nrhs})$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

**7 Accuracy**

The computed solution for a single right-hand side,  $\hat{x}$ , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and  $\epsilon$  is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where  $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$ , the condition number of  $A$  with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

Following the use of this function nag\_zptcon (f07juc) can be used to estimate the condition number of  $A$  and nag\_zptrfs (f07jvc) can be used to obtain approximate error bounds.

**8 Parallelism and Performance**

nag\_zpttrs (f07jsc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The total number of floating-point operations required to solve the equations  $AX = B$  is proportional to  $nr$ .

The real analogue of this function is nag\_dpttrs (f07jec).

## 10 Example

This example solves the equations

$$AX = B,$$

where  $A$  is the Hermitian positive definite tridiagonal matrix

$$A = \begin{pmatrix} 16.0 & 16.0 - 16.0i & 0 & 0 \\ 16.0 + 16.0i & 41.0 & 18.0 + 9.0i & 0.0 \\ 0 & 18.0 - 9.0i & 46.0 & 1.0 + 4.0i \\ 0 & 0 & 1.0 - 4.0i & 21.0 \end{pmatrix}$$

and

$$B = \begin{pmatrix} 64.0 + 16.0i & -16.0 - 32.0i \\ 93.0 + 62.0i & 61.0 - 66.0i \\ 78.0 - 80.0i & 71.0 - 74.0i \\ 14.0 - 27.0i & 35.0 + 15.0i \end{pmatrix}.$$

### 10.1 Program Text

```
/* nag_zpttrs (f07jsc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf07.h>

int main(void)
{
    /* Scalars */
    Integer exit_status = 0, i, j, n, nrhs, pdb;
    Nag_OrderType order;

    /* Arrays */
    Complex *b = 0, *e = 0;
    double *d = 0;

    /* Nag Types */
    NagError fail;

#ifdef NAG_COLUMN_MAJOR
#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
```

```

    printf("nag_zpttrs (f07jsc) Example Program Results\n\n");
    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%*[\n]", &n, &nrhs);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%*[\n]", &n, &nrhs);
#endif
    if (n < 0 || nrhs < 0) {
        printf("Invalid n or nrhs\n");
        exit_status = 1;
        goto END;
    }
    /* Allocate memory */
    if (!(b = NAG_ALLOC(n * nrhs, Complex)) ||
        !(e = NAG_ALLOC(n - 1, Complex)) || !(d = NAG_ALLOC(n, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
#ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

    /* Read the upper bidiagonal part of the tridiagonal matrix A from */
    /* data file */
#ifdef _WIN32
    for (i = 0; i < n - 1; ++i)
        scanf_s(" ( %lf , %lf )", &e[i].re, &e[i].im);
#else
    for (i = 0; i < n - 1; ++i)
        scanf(" ( %lf , %lf )", &e[i].re, &e[i].im);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    for (i = 0; i < n; ++i)
        scanf_s("%lf", &d[i]);
#else
    for (i = 0; i < n; ++i)
        scanf("%lf", &d[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

    /* Read the right hand matrix B */
    for (i = 1; i <= n; ++i)
        for (j = 1; j <= nrhs; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
            scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");

```

```

#endif

/* Factorize the tridiagonal matrix A using nag_zpttrf (f07jrc). */
nag_zpttrf(n, d, e, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zpttrf (f07jrc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Solve the equations AX = B using nag_zpttrs (f07jsc). */
nag_zpttrs(order, Nag_Upper, n, nrhs, d, e, b, pdb, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zpttrs (f07jsc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print the solution using nag_gen_complx_mat_print_comp (x04dbc). */
fflush(stdout);
nag_gen_complx_mat_print_comp(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                               nrhs, b, pdb, Nag_BracketForm, "%7.4f",
                               "Solution(s)", Nag_IntegerLabels, 0,
                               Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
}
END:
NAG_FREE(b);
NAG_FREE(e);
NAG_FREE(d);

return exit_status;
}

#undef B

```

## 10.2 Program Data

```

nag_zpttrs (f07jrc) Example Program Data
      4          2
( 16.0,-16.0) ( 18.0,  9.0) (  1.0,  4.0)      : n, nrhs
      16.0      41.0      46.0      21.0      : sub-diagonal e
      64.0, 16.0) (-16.0,-32.0)
      93.0, 62.0) ( 61.0,-66.0)
      78.0,-80.0) ( 71.0,-74.0)
      14.0,-27.0) ( 35.0, 15.0)                : diagonal D
                                           : matrix B

```

## 10.3 Program Results

nag\_zpttrs (f07jrc) Example Program Results

```

Solution(s)
           1          2
1 ( 2.0000, 1.0000) (-3.0000,-2.0000)
2 ( 1.0000, 1.0000) ( 1.0000, 1.0000)
3 ( 1.0000,-2.0000) ( 1.0000,-2.0000)
4 ( 1.0000,-1.0000) ( 2.0000, 1.0000)

```

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