

NAG Library Function Document

nag_dgttrs (f07cec)

1 Purpose

nag_dgttrs (f07cec) computes the solution to a real system of linear equations $AX = B$ or $A^T X = B$, where A is an n by n tridiagonal matrix and X and B are n by r matrices, using the LU factorization returned by nag_dgttrf (f07cdc).

2 Specification

```
#include <nag.h>
#include <nagf07.h>

void nag_dgttrs (Nag_OrderType order, Nag_TransType trans, Integer n,
                 Integer nrhs, const double dl[], const double d[], const double du[],
                 const double du2[], const Integer ipiv[], double b[], Integer pdb,
                 NagError *fail)
```

3 Description

nag_dgttrs (f07cec) should be preceded by a call to nag_dgttrf (f07cdc), which uses Gaussian elimination with partial pivoting and row interchanges to factorize the matrix A as

$$A = PLU,$$

where P is a permutation matrix, L is unit lower triangular with at most one nonzero subdiagonal element in each column, and U is an upper triangular band matrix, with two superdiagonals. nag_dgttrs (f07cec) then utilizes the factorization to solve the required equations.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **trans** – Nag_TransType *Input*

On entry: specifies the equations to be solved as follows:

trans = Nag_NoTrans
Solve $AX = B$ for X .

trans = Nag_Trans or Nag_ConjTrans
Solve $A^T X = B$ for X .

Constraint: **trans** = Nag_NoTrans, Nag_Trans or Nag_ConjTrans.

- 3: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.
- 4: **nrhs** – Integer *Input*
On entry: r , the number of right-hand sides, i.e., the number of columns of the matrix B .
Constraint: $\mathbf{nrhs} \geq 0$.
- 5: **dl**[dim] – const double *Input*
Note: the dimension, dim , of the array **dl** must be at least $\max(1, \mathbf{n} - 1)$.
On entry: must contain the $(n - 1)$ multipliers that define the matrix L of the LU factorization of A .
- 6: **d**[dim] – const double *Input*
Note: the dimension, dim , of the array **d** must be at least $\max(1, \mathbf{n})$.
On entry: must contain the n diagonal elements of the upper triangular matrix U from the LU factorization of A .
- 7: **du**[dim] – const double *Input*
Note: the dimension, dim , of the array **du** must be at least $\max(1, \mathbf{n} - 1)$.
On entry: must contain the $(n - 1)$ elements of the first superdiagonal of U .
- 8: **du2**[dim] – const double *Input*
Note: the dimension, dim , of the array **du2** must be at least $\max(1, \mathbf{n} - 2)$.
On entry: must contain the $(n - 2)$ elements of the second superdiagonal of U .
- 9: **ipiv**[dim] – const Integer *Input*
Note: the dimension, dim , of the array **ipiv** must be at least $\max(1, \mathbf{n})$.
On entry: must contain the n pivot indices that define the permutation matrix P . At the i th step, row i of the matrix was interchanged with row **ipiv**[$i - 1$], and **ipiv**[$i - 1$] must always be either i or $(i + 1)$, **ipiv**[$i - 1$] = i indicating that a row interchange was not performed.
- 10: **b**[dim] – double *Input/Output*
Note: the dimension, dim , of the array **b** must be at least
 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** = Nag_ColMajor;
 $\max(1, \mathbf{n} \times \mathbf{pdb})$ when **order** = Nag_RowMajor.
The (i, j) th element of the matrix B is stored in
 $\mathbf{b}[(j - 1) \times \mathbf{pdb} + i - 1]$ when **order** = Nag_ColMajor;
 $\mathbf{b}[(i - 1) \times \mathbf{pdb} + j - 1]$ when **order** = Nag_RowMajor.
On entry: the n by r matrix of right-hand sides B .
On exit: the n by r solution matrix X .
- 11: **pdb** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.

Constraints:

if **order** = Nag_ColMajor, **pdb** $\geq \max(1, \mathbf{n})$;
 if **order** = Nag_RowMajor, **pdb** $\geq \max(1, \mathbf{nrhs})$.

12: **fail** – NagError *

Input/Output

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, **n** = $\langle value \rangle$.

Constraint: **n** ≥ 0 .

On entry, **nrhs** = $\langle value \rangle$.

Constraint: **nrhs** ≥ 0 .

On entry, **pdb** = $\langle value \rangle$.

Constraint: **pdb** > 0 .

NE_INT_2

On entry, **pdb** = $\langle value \rangle$ and **n** = $\langle value \rangle$.

Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$ and **nrhs** = $\langle value \rangle$.

Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

7 Accuracy

The computed solution for a single right-hand side, \hat{x} , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and ϵ is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$, the condition number of A with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

Following the use of this function nag_dgtcon (f07cgc) can be used to estimate the condition number of A and nag_dgtrfs (f07chc) can be used to obtain approximate error bounds.

8 Parallelism and Performance

nag_dgttrs (f07cec) is not threaded in any implementation.

9 Further Comments

The total number of floating-point operations required to solve the equations $AX = B$ or $A^T X = B$ is proportional to nr .

The complex analogue of this function is nag_zgttrs (f07csc).

10 Example

This example solves the equations

$$AX = B,$$

where A is the tridiagonal matrix

$$A = \begin{pmatrix} 3.0 & 2.1 & 0 & 0 & 0 \\ 3.4 & 2.3 & -1.0 & 0 & 0 \\ 0 & 3.6 & -5.0 & 1.9 & 0 \\ 0 & 0 & 7.0 & -0.9 & 8.0 \\ 0 & 0 & 0 & -6.0 & 7.1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2.7 & 6.6 \\ -0.5 & 10.8 \\ 2.6 & -3.2 \\ 0.6 & -11.2 \\ 2.7 & 19.1 \end{pmatrix}.$$

10.1 Program Text

```
/* nag_dgttrs (f07cec) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */
#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf07.h>

int main(void)
{
    /* Scalars */
    Integer exit_status = 0, i, j, n, nrhs, pdb;

    /* Arrays */
    double *b = 0, *d = 0, *dl = 0, *du = 0, *du2 = 0;
    Integer *ipiv = 0;

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;

#ifdef NAG_COLUMN_MAJOR
```

```

#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_dgttrs (f07cec) Example Program Results\n\n");
    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%*[\n]", &n, &nrhs);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%*[\n]", &n, &nrhs);
#endif
    if (n < 0 || nrhs < 0) {
        printf("Invalid n or nrhs\n");
        exit_status = 1;
        goto END;
    }
    /* Allocate memory */
    if (!(b = NAG_ALLOC(n * nrhs, double)) ||
        !(d = NAG_ALLOC(n, double)) ||
        !(dl = NAG_ALLOC(n - 1, double)) ||
        !(du = NAG_ALLOC(n - 1, double)) ||
        !(du2 = NAG_ALLOC(n - 2, double)) || !(ipiv = NAG_ALLOC(n, Integer)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

#ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

    /* Read the tridiagonal matrix A from data file */
#ifdef _WIN32
    for (i = 0; i < n - 1; ++i)
        scanf_s("%lf", &du[i]);
#else
    for (i = 0; i < n - 1; ++i)
        scanf("%lf", &du[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    for (i = 0; i < n; ++i)
        scanf_s("%lf", &d[i]);
#else
    for (i = 0; i < n; ++i)
        scanf("%lf", &d[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32

```

```

    for (i = 0; i < n - 1; ++i)
        scanf_s("%lf", &dl[i]);
#else
    for (i = 0; i < n - 1; ++i)
        scanf("%lf", &dl[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[^\\n]");
#else
    scanf("%*[^\\n]");
#endif

    /* Read the right hand matrix B */

    for (i = 1; i <= n; ++i)
#ifdef _WIN32
        for (j = 1; j <= nrhs; ++j)
            scanf_s("%lf", &B(i, j));
#else
        for (j = 1; j <= nrhs; ++j)
            scanf("%lf", &B(i, j));
#endif
#ifdef _WIN32
    scanf_s("%*[^\\n]");
#else
    scanf("%*[^\\n]");
#endif

    /* Factorize the tridiagonal matrix A using nag_dgttrf (f07cdc). */
    nag_dgttrf(n, dl, d, du, du2, ipiv, &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_dgttrf (f07cdc).\\n%s\\n", fail.message);
        exit_status = 1;
        goto END;
    }

    /* Solve the equations AX = B using nag_dgttrs (f07cec). */
    nag_dgttrs(order, Nag_NoTrans, n, nrhs, dl, d, du, du2, ipiv, b, pdb,
        &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_dgttrs (f07cec).\\n%s\\n", fail.message);
        exit_status = 1;
        goto END;
    }

    /* Print the solution usbing nag_gen_real_mat_print (x04cac). */
    fflush(stdout);
    nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs,
        b, pdb, "Solution(s)", 0, &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_gen_real_mat_print (x04cac).\\n%s\\n", fail.message);
        exit_status = 1;
        goto END;
    }
}
END:
    NAG_FREE(b);
    NAG_FREE(d);
    NAG_FREE(dl);
    NAG_FREE(du);
    NAG_FREE(du2);
    NAG_FREE(ipiv);
    return exit_status;
}

#undef B

```

10.2 Program Data

```
nag_dgttrs (f07cec) Example Program Data
  5      2      : n and nrhs
      2.1 -1.0  1.9  8.0
  3.0  2.3 -5.0 -0.9  7.1
  3.4  3.6  7.0 -6.0      : matrix A
  2.7  6.6
-0.5 10.8
  2.6 -3.2
  0.6 -11.2
  2.7 19.1      : matrix B
```

10.3 Program Results

```
nag_dgttrs (f07cec) Example Program Results
```

```
Solution(s)
      1      2
  1 -4.0000  5.0000
  2  7.0000 -4.0000
  3  3.0000 -3.0000
  4 -4.0000 -2.0000
  5 -3.0000  1.0000
```
