NAG Library Function Document

nag_1d_quad_osc_1 (d01skc)

1 Purpose

nag_1d_quad_osc_1 (d01skc) is an adaptive integrator, especially suited to oscillating, nonsingular integrands, which calculates an approximation to the integral of a function $f(x)$ over a finite interval $[a,b]$:

$$I = \int_a^b f(x)dx.$$

2 Specification

```
#include <nag.h>
#include <nagd01.h>
void nag_1d_quad_osc_1 (
     double (*f)(double x, Nag_User *comm),
     double a, double b, double epsabs, double epsrel,
     Integer max_num_subint, double *result, double *abserr,
     Nag_QuadProgress *qp, Nag_User *comm, NagError *fail)
```

3 Description

nag_1d_quad_osc_1 (d01skc) is based upon the QUADPACK routine QAG (Piessens *et al.* (1983)). It is an adaptive function, using the Gauss 30-point and Kronrod 61-point rules. A 'global' acceptance criterion (as defined by Malcolm and Simpson (1976)) is used. The local error estimation is described by Piessens *et al.* (1983).

As this function is based on integration rules of high order, it is especially suitable for nonsingular oscillating integrands.

This function requires you to supply a function to evaluate the integrand at a single point.

4 References

Malcolm M A and Simpson R B (1976) Local versus global strategies for adaptive quadrature *ACM Trans. Math. Software* **1** 129–146

Piessens R (1973) An algorithm for automatic integration *Angew. Inf.* **15** 399–401

Piessens R, de Doncker–Kapenga E, Ûberhuber C and Kahaner D (1983) *QUADPACK, A Subroutine Package for Automatic Integration* Springer–Verlag

5 Arguments

1: **f** – function, supplied by the user *External Function*

f must return the value of the integrand f at a given point.

The specification of **f** is:

```
double f (double x, Nag_User *comm)
```

1: **x** – double *Input*

On entry: the point at which the integrand f must be evaluated.

2: **comm** – Nag_User *

Pointer to a structure of type Nag_User with the following member:

p – Pointer

On entry/exit: the pointer **comm→p** should be cast to the required type, e.g., `struct user *s = (struct user *)comm → p`, to obtain the original object's address with appropriate type. (See the argument **comm** below.)

2: **a** – double *Input*

On entry: the lower limit of integration, a.

3: **b** – double *Input*

On entry: the upper limit of integration, b. It is not necessary that $a < b$.

4: **epsabs** – double *Input*

On entry: the absolute accuracy required. If **epsabs** is negative, the absolute value is used. See Section 7.

5: **epsrel** – double *Input*

On entry: the relative accuracy required. If **epsrel** is negative, the absolute value is used. See Section 7.

6: **max_num_subint** – Integer *Input*

On entry: the upper bound on the number of sub-intervals into which the interval of integration may be divided by the function. The more difficult the integrand, the larger **max_num_subint** should be.

Constraint: **max_num_subint** ≥ 1.

7: **result** – double * *Output*

On exit: the approximation to the integral I.

8: **abserr** – double * *Output*

On exit: an estimate of the modulus of the absolute error, which should be an upper bound for $|I -$ **result**$|$.

9: **qp** – Nag_QuadProgress *

Pointer to structure of type Nag_QuadProgress with the following members:

num_subint – Integer *Output*

On exit: the actual number of sub-intervals used.

fun_count – Integer *Output*

On exit: the number of function evaluations performed by nag_1d_quad_osc_1 (d01skc).

sub_int_beg_pts – double * *Output*
sub_int_end_pts – double * *Output*
sub_int_result – double * *Output*
sub_int_error – double * *Output*

On exit: these pointers are allocated memory internally with **max_num_subint** elements. If an error exit other than NE_INT_ARG_LT or NE_ALLOC_FAIL occurs, these arrays will contain information which may be useful. For details, see Section 9.

Before a subsequent call to nag_1d_quad_osc_1 (d01skc) is made, or when the information contained in these arrays is no longer useful, you should free the storage allocated by these pointers using the NAG macro `NAG_FREE`.

10: **comm** – Nag_User *

Pointer to a structure of type Nag_User with the following member:

p – Pointer

On entry/exit: the pointer **comm→p**, of type Pointer, allows you to communicate information to and from **f**(). An object of the required type should be declared, e.g., a structure, and its address assigned to the pointer **comm→p** by means of a cast to Pointer in the calling program, e.g., `comm.p = (Pointer)&s`. The type Pointer is `void *`.

11: **fail** – NagError * *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_INT_ARG_LT

On entry, **max_num_subint** must not be less than 1: **max_num_subint** $= \langle value \rangle$.

NE_QUAD_BAD_SUBDIV

Extremely bad integrand behaviour occurs around the sub-interval $(\langle value \rangle, \langle value \rangle)$.
The same advice applies as in the case of NE_QUAD_MAX_SUBDIV.

NE_QUAD_MAX_SUBDIV

The maximum number of subdivisions has been reached: **max_num_subint** $= \langle value \rangle$.

The maximum number of subdivisions has been reached without the accuracy requirements being achieved. Look at the integrand in order to determine the integration difficulties. If the position of a local difficulty within the interval can be determined (e.g., a singularity of the integrand or its derivative, a peak, a discontinuity, etc.) you will probably gain from splitting up the interval at this point and calling the integrator on the sub-intervals. If necessary, another integrator, which is designed for handling the type of difficulty involved, must be used. Alternatively, consider relaxing the accuracy requirements specified by **epsabs** and **epsrel**, or increasing the value of **max_num_subint**.

NE_QUAD_ROUNDOFF_TOL

Round-off error prevents the requested tolerance from being achieved: **epsabs** $= \langle value \rangle$, **epsrel** $= \langle value \rangle$.
The error may be underestimated. Consider relaxing the accuracy requirements specified by **epsabs** and **epsrel**.

7 Accuracy

nag_1d_quad_osc_1 (d01skc) cannot guarantee, but in practice usually achieves, the following accuracy:

$$|I - \mathbf{result}| \leq tol$$

where

$$tol = \max\{|\mathbf{epsabs}|, |\mathbf{epsrel}| \times |I|\}$$

and **epsabs** and **epsrel** are user-specified absolute and relative error tolerances. Moreover it returns the quantity **abserr** which, in normal circumstances, satisfies

$$|I - \mathbf{result}| \le \mathbf{abserr} \le tol.$$

8 Parallelism and Performance

nag_1d_quad_osc_1 (d01skc) is not threaded in any implementation.

9 Further Comments

The time taken by nag_1d_quad_osc_1 (d01skc) depends on the integrand and the accuracy required.

If the function fails with an error exit other than NE_INT_ARG_LT or NE_ALLOC_FAIL, then you may wish to examine the contents of the structure **qp**. These contain the end-points of the sub-intervals used by nag_1d_quad_osc_1 (d01skc) along with the integral contributions and error estimates over these sub-intervals.

Specifically, $i = 1, 2, \ldots, n$, let r_i denote the approximation to the value of the integral over the sub-interval $[a_i, b_i]$ in the partition of $[a, b]$ and e_i be the corresponding absolute error estimate.

Then, $\int_{a_i}^{b_i} f(x)dx \simeq r_i$ and $\mathbf{result} = \sum_{i=1}^{n} r_i$. The value of n is returned in **qp→num_subint**, and the values a_i, b_i, r_i and e_i are stored in the structure **qp** as

$a_i = \mathbf{qp{\to}sub\_int\_beg\_pts}[i-1]$,

$b_i = \mathbf{qp{\to}sub\_int\_end\_pts}[i-1]$,

$r_i = \mathbf{qp{\to}sub\_int\_result}[i-1]$ and

$e_i = \mathbf{qp{\to}sub\_int\_error}[i-1]$.

10 Example

This example computes

$$\int_0^{2\pi} \sin(30x) \cos x dx.$$

10.1 Program Text

```
/* nag_1d_quad_osc_1 (d01skc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 *
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <math.h>
#include <nagd01.h>
#include <nagx01.h>

#ifdef __cplusplus
extern "C"
{
#endif
  static double NAG_CALL f(double x, Nag_User *comm);
```

```
#ifdef __cplusplus
}
#endif

int main(void)
{
  static Integer use_comm[1] = { 1 };
  Integer exit_status = 0;
  double a, b;
  double epsabs, abserr, epsrel, result;
  Nag_QuadProgress qp;
  Integer max_num_subint;
  NagError fail;
  /* nag_pi (x01aac).
   * pi
   */
  double pi = nag_pi;
  Nag_User comm;

  INIT_FAIL(fail);

  printf("nag_1d_quad_osc_1 (d01skc) Example Program Results\n");

  /* For communication with user-supplied functions: */
  comm.p = (Pointer) &use_comm;

  epsabs = 0.0;
  epsrel = 0.001;
  a = 0.0;
  b = pi * 2.0;
  max_num_subint = 200;

  /* nag_1d_quad_osc_1 (d01skc).
   * One-dimensional adaptive quadrature, suitable for
   * oscillating functions, thread-safe
   */
  nag_1d_quad_osc_1(f, a, b, epsabs, epsrel, max_num_subint, &result, &abserr,
                    &qp, &comm, &fail);
  printf("a      - lower limit of integration = %10.4f\n", a);
  printf("b      - upper limit of integration = %10.4f\n", b);
  printf("epsabs - absolute accuracy requested = %11.2e\n", epsabs);
  printf("epsrel - relative accuracy requested = %11.2e\n\n", epsrel);
  if (fail.code != NE_NOERROR)
    printf("Error from nag_1d_quad_osc_1 (d01skc) %s\n", fail.message);
  if (fail.code != NE_INT_ARG_LT && fail.code != NE_ALLOC_FAIL &&
      fail.code != NE_NO_LICENCE) {
    printf("result - approximation to the integral = %9.5f\n", result);
    printf("abserr - estimate of the absolute error = %11.2e\n", abserr);
    printf("qp.fun_count  - number of function evaluations = %4" NAG_IFMT
           "\n", qp.fun_count);
    printf("qp.num_subint  - number of subintervals used = %4" NAG_IFMT "\n",
           qp.num_subint);
    /* Free memory used by qp */
    NAG_FREE(qp.sub_int_beg_pts);
    NAG_FREE(qp.sub_int_end_pts);
    NAG_FREE(qp.sub_int_result);
    NAG_FREE(qp.sub_int_error);
  }
  else {
    exit_status = 1;
    goto END;
  }

END:
  return exit_status;
}

static double NAG_CALL f(double x, Nag_User *comm)
{
  Integer *use_comm = (Integer *) comm->p;
```

```
  if (use_comm[0]) {
    printf("(User-supplied callback f, first invocation.)\n");
    use_comm[0] = 0;
  }

  return x * sin(x * 30.0) * cos(x);
}
```

10.2 Program Data

None.

10.3 Program Results

```
nag_1d_quad_osc_1 (d01skc) Example Program Results
(User-supplied callback f, first invocation.)
a      - lower limit of integration =     0.0000
b      - upper limit of integration =     6.2832
epsabs - absolute accuracy requested =    0.00e+00
epsrel - relative accuracy requested =    1.00e-03

result - approximation to the integral =  -0.20967
abserr - estimate of the absolute error =    4.48e-14
qp.fun_count  - number of function evaluations =  427
qp.num_subint  - number of subintervals used =    4
```